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GUI : FINGERPRINT SOFTWARE GUIDELINE FOR USER

Open the SFGDemo software and select "Open Device". Choose the COM port used by the Arduino (Notice that the COM provided only from COM1-COM16).



The software will show "Open Device Success" and "hardware information" on the screen. Then, change the baud rate and security level in the bottom left hand corner, as well as the "security level" (how sensitive it is). Set it to 57600 baud and security level 3.

	Open Device Success!
	Cancel Operate Exit Image Manage Capture Con Capture Save Image Capture Con Capture Save Image Download Image Enroll Preview Enroll Con Enroll Match Template Database 0 Match Empty
English Finger Database: 162 Secure Level: 3 Address: 0xfmmf Package Size: 128 bytes Bandrate: 57600 bps Product Type:ZFM30411 Version:20090508	Search Con Search Quick Search Special
Manufacture:ZhiAnTec Sensor:ZFS-20	Read Notepad Random Capture Image DB Write Notepad Valid Template
Open Device(()) Communicate with COM7	Deal with image Path
Baudrate Package Size Secure Level	Course Din Image Thin Image Template Image



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To enroll the new finger, clic 'Continuous' enroll, which yo by type "#" and followed by	k on the Preview checkbox and press the Enroll button. (Con Enroll means ou may enroll for others fingerprint. When the box comes up, key in the ID the number you desire. You can use up to 162 ID numbers
by type $\#$ and followed by	Upper address
	Setting
	Address 3
	OK Cancel
The software will ask you to	press the finger on the sensor.
Please	put your imger to sensor:
	Cancel Onerate Evit
You can then see a image of	anage
SFG Demo	
Image Preview	Please put your finger to sensor!
iiiiiii.	Trease put your iniger to sensor:
	Cancel Onerate Evit
	Capture Con Capture Save Image Download Image
1111 13	Preview Enroll Con Enroll
99 (19 9) (1	Match Template Database
	Autress Finite Empty
To get a second fingerprint	you have to repeat the process. You will get the potice if it success
	ou have to repeat the process. Fou will get the notice if it success.
	Success to enroll!
	Cancel Operate Exit