SYNACORP TECHNOLOGIES SDN. BHD. (1310487-K)

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REF: FR1-18B20

DS18B20 Temperature Sensor 18B20 TO-92



Description

The DS18B20 is a 1-Wire® temperature sensor manufactured by Dallas Semiconductor (acquired by Maxim Integrated). Because it is a 1-wire device, it only needs one digital pin to communicate with the microcontroller. The sensor is typically available in two form factors. One comes in a TO-92 package, which resembles a simple transistor. The other comes in the form of a waterproof probe, which is more useful when measuring something far away, underwater, or beneath the ground.

Specifications

IC output type: digital

Sensing accuracy range: ± 0.5°C

Temperature detection range: -55°C to +125°C

Supply current: 1mA

Supply voltage range: 3V to 5.5V

Resolution, bit: 12bit

Package Type:TO-92

Number of pins: 3

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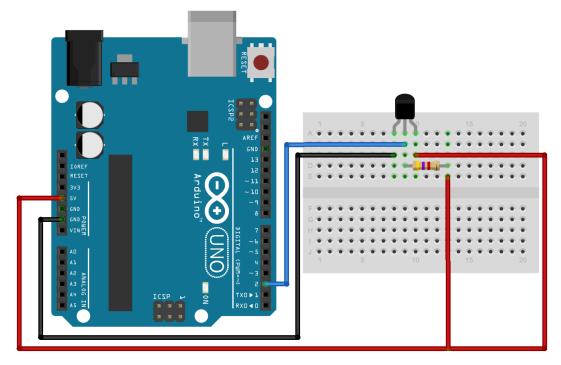
Pin connection

The connections are straightforward. Begin by connecting VDD to the Arduino's 5V pin and GND to ground. Connect the signal pin DQ to Arduino's digital pin 2. To keep the data transfer stable, you'll also need to connect the 4.7k pull-up resistor between the signal and power pins (Note: internal pull-ups on the arduino do not work here). To avoid overheating and damage, make sure the DS18B20 is connected properly.

Adruino uno (PIN)	DS18B20 (PIN)
5V	VDD
GND	GND
D2	DQ
5V	4.7K pullup resistor

Circuit diagram

Connect the signal pin DQ to Arduino's digital pin 2. To keep the data transfer stable, you'll also need to connect the 4.7k pull-up resistor between the signal and power pins (Note: internal pull-ups on the arduino do not work here).

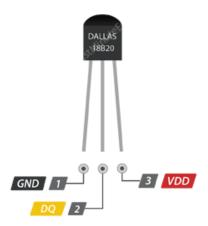


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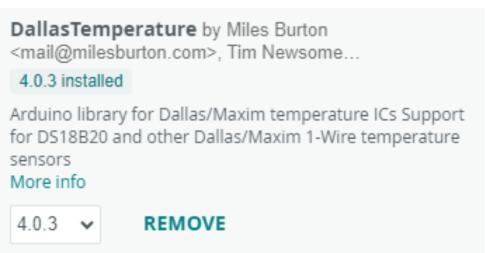
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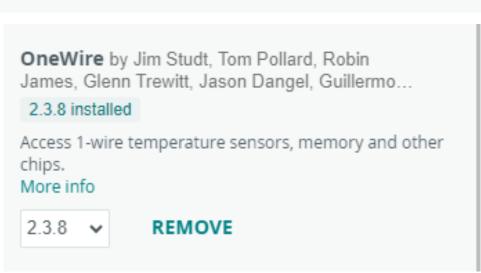
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Pin diagram



Library





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CODING

The sketch below will provide you with a thorough understanding of how to read temperature readings from a DS18B20 Temperature Sensor and can serve as the foundation for more practical experiments and projects.

```
Tester.ino
   #include <OneWire.h>
       #include <DallasTemperature.h>
       // Data wire is plugged into digital pin 2 on the Arduino
       #define ONE WIRE BUS 2
       // Setup a oneWire instance to communicate with any OneWire device
       OneWire oneWire(ONE_WIRE_BUS);
       // Pass oneWire reference to DallasTemperature library
  10
       DallasTemperature sensors(&oneWire);
  12
       void setup(void)
  13
  14
         sensors.begin(); // Start up the library
  16
         Serial.begin(9600);
  17
  18
       void loop(void)
  20
  21
         // Send the command to get temperatures
  22
         sensors.requestTemperatures();
  24
         //print the temperature in Celsius
         Serial.print("Temperature: "):
  25
         Serial.print(sensors.getTempCByIndex(0));
  26
         Serial.print((char)176);//shows degrees character
         Serial.print("C | ");
  29
  30
         //print the temperature in Fahrenheit
         Serial.print((sensors.getTempCByIndex(0) * 9.0) / 5.0 + 32.0);
  31
         Serial.print((char)176);//shows degrees character
  33
        Serial.println("F");
  34
         delay(500);
```

Result

Here's what the output looks like on the serial monitor

```
11:15:44.329 -> Temperature: 29.25&C | 84.65&F
11:15:44.968 -> Temperature: 29.31 C | 84.76 F
11:15:45.493 -> Temperature: 29.31 C | 84.76 F
11:15:46.138 -> Temperature: 29.25 C | 84.65 F
11:15:46.721 -> Temperature: 29.25♦C | 84.65♦F
11:15:47.307 -> Temperature: 29.25�C | 84.65�F
11:15:47.848 -> Temperature: 29.25�C | 84.65�F
11:15:48.578 -> Temperature: 29.31 C
11:15:49.040 -> Temperature: 29.31 C | 84.76 F
11:15:49.641 -> Temperature: 29.31 C | 84.76 F
11:15:50.230 -> Temperature: 29.31 C | 84.76 F
11:15:50.840 -> Temperature: 29.31 C | 84.76 F
11:15:51.381 -> Temperature: 29.310C | 84.760F
11:15:52.000 -> Temperature: 29.31 C
11:15:52.586 -> Temperature: 29.31 C
                                       84.76©F
11:15:53.189 -> Temperature: 29.25 C | 84.65 F
```